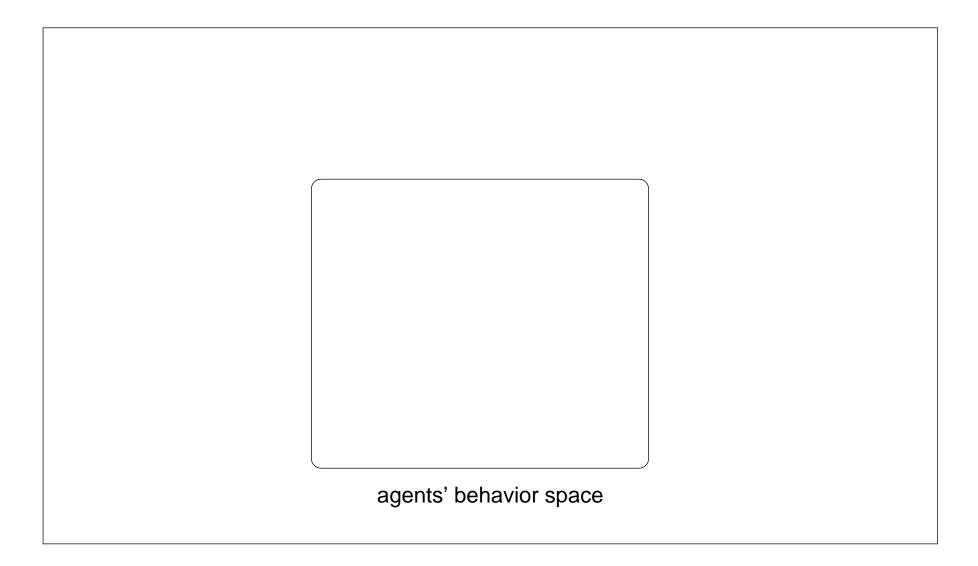
Using the *M*oise⁺ Organisational Model for a Cooperative Framework of MAS Reorganisation

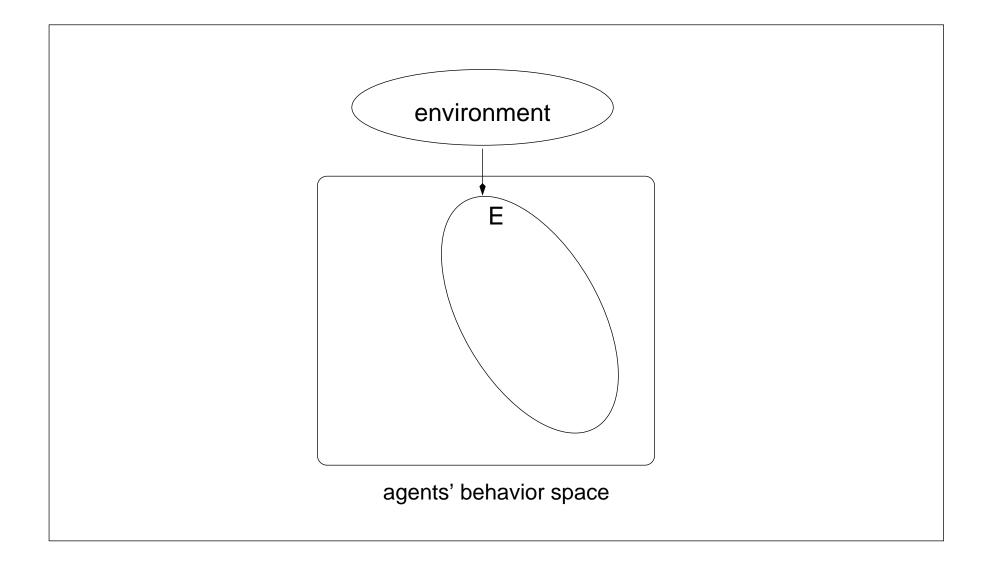
Jomi Fred Hübner, Jaime Simão Sichman, and Olivier Boissier FURB/DSC & USP/LTI & ENSM.SE/SMA

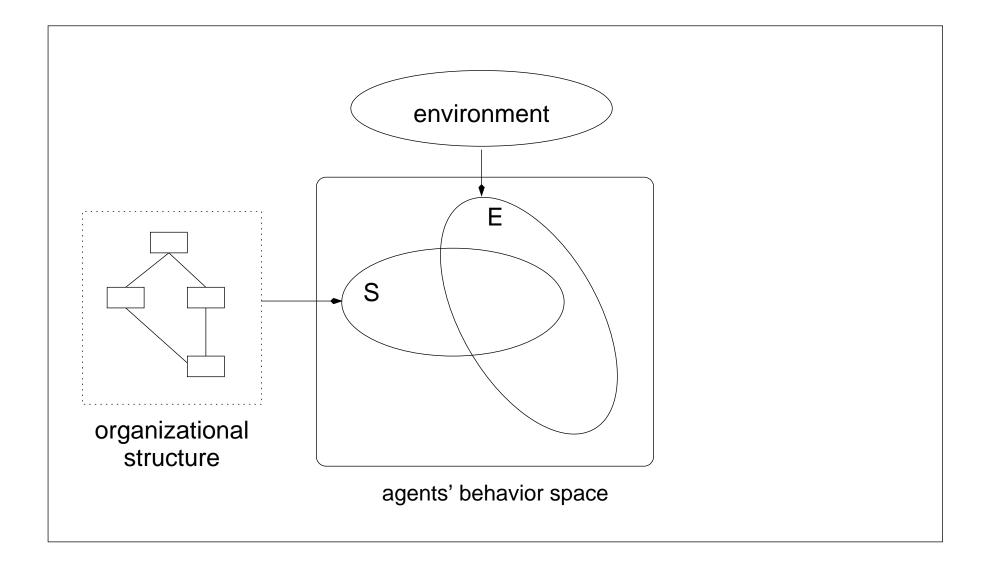
SBIA'2004, São Luis, Brazil

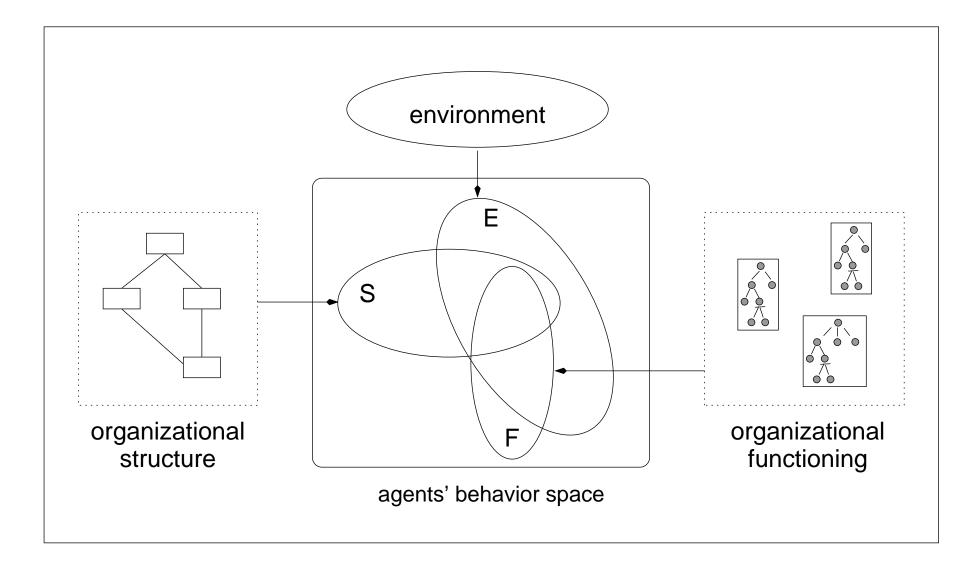
Context

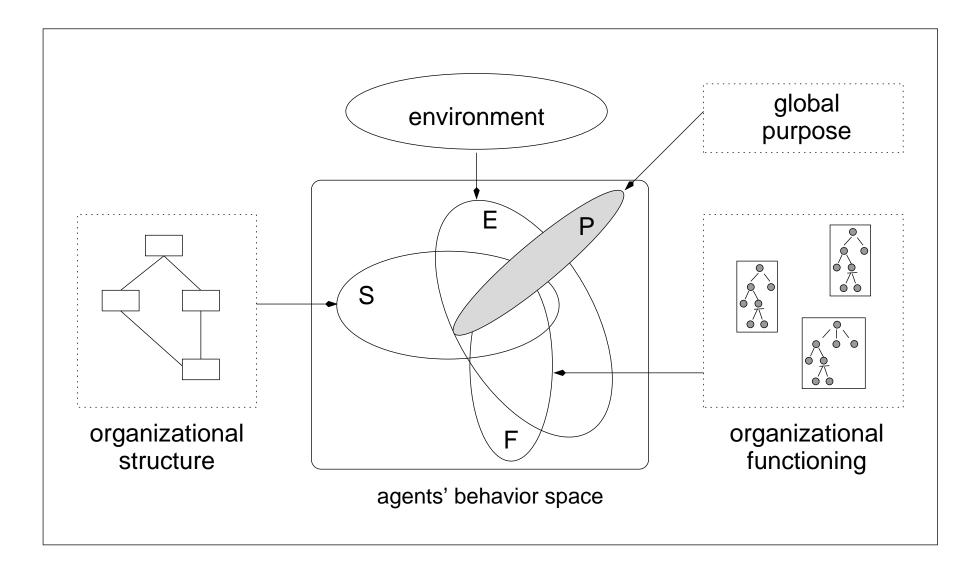
- A multiagent system has two properties which seems controversial:
 - \star a **global** purpose \times **autonomous** agents
 - While the autonomy of the agents is essential for the MAS, it may cause the looseness of the global congruence.
- The organisation of an MAS is used to solve this conflict constraining the agents' behaviour towards global purposes.
- Example: when an agent adopts a role, it indeed adopts a set of behavioural constraints that collaborates for a global purpose.



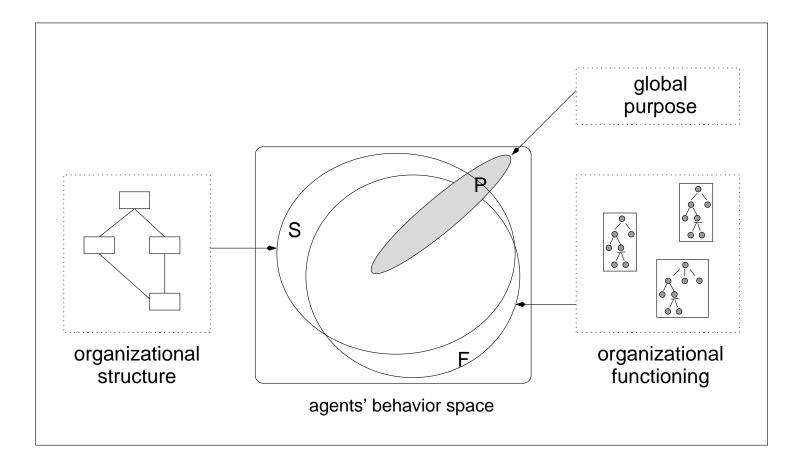






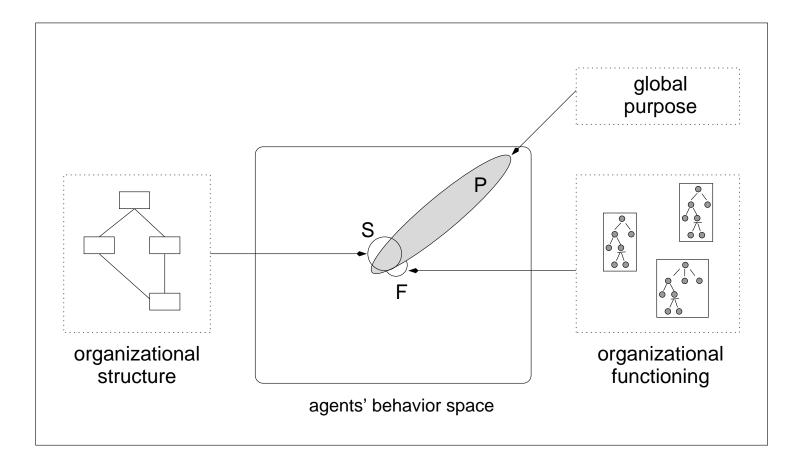


The **problem** of finding a good organisation



(the organisation does not help to global purpose)

The **problem** of finding a good organisation



(the organisation extinguish the agents' autonomy)

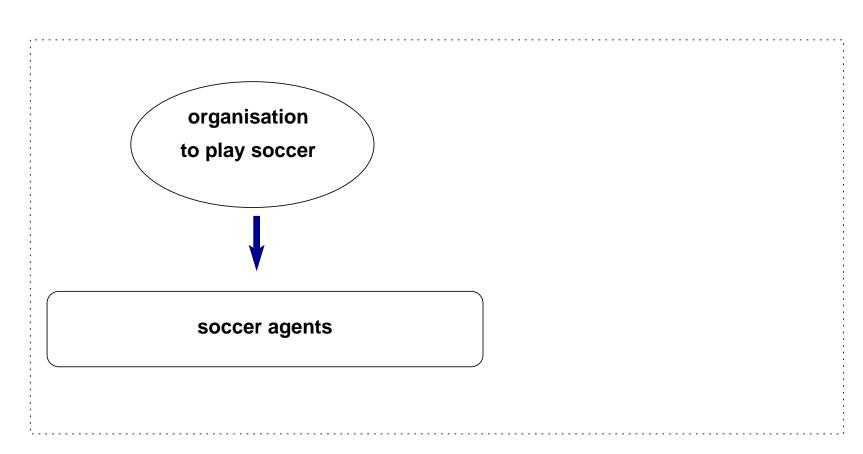
The problem of finding a good organisation on **dynamic** environment

- Initially, the problem can be solved by the MAS designer.
- On dynamic and open environments, the agents themselves must change its organisation.

 \star reorganisation

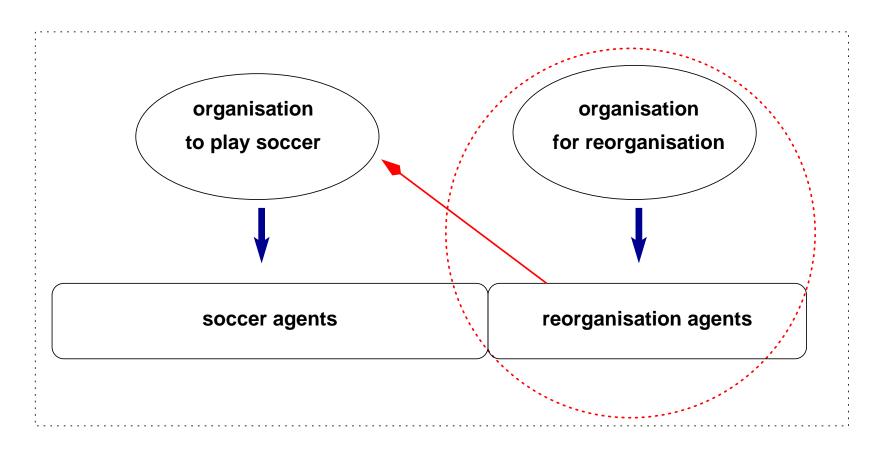
Study Case: Robocup small size league

K TBSim (jomilze.la	r)	
File View		Help
	reset/reload start/resume pause	2
score: 0:0 shot: 60		

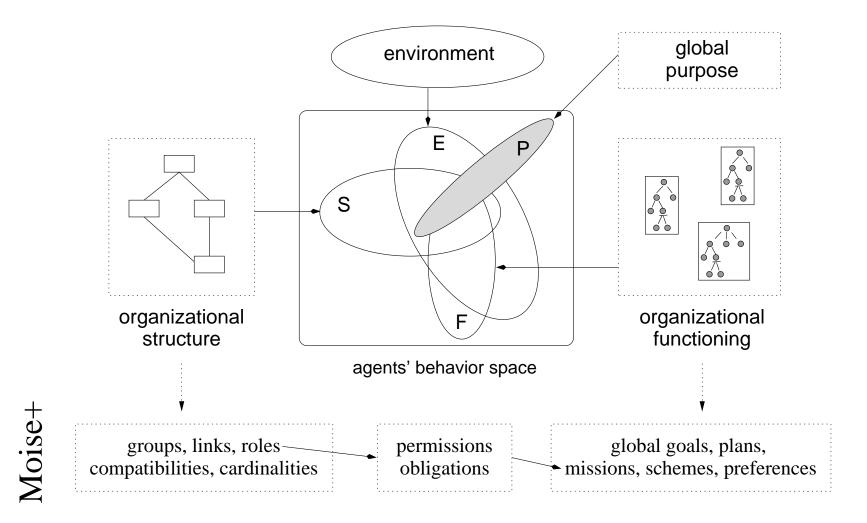


$\operatorname{JOJTEAM}$ organisation

Our approach

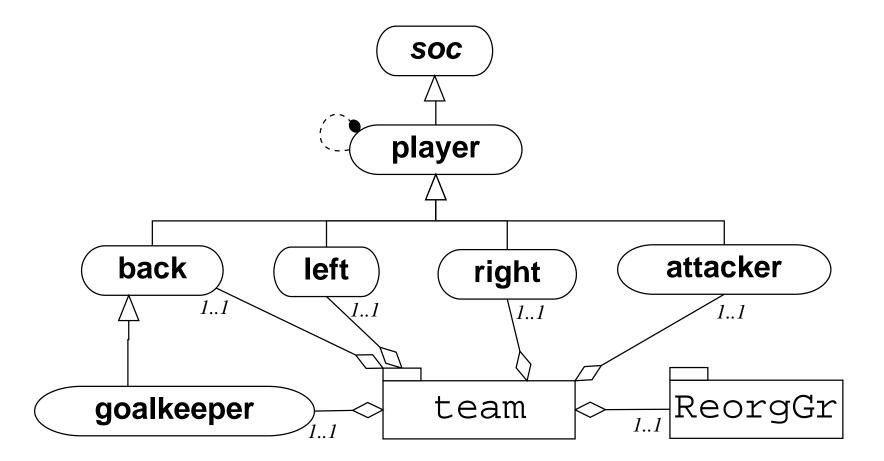


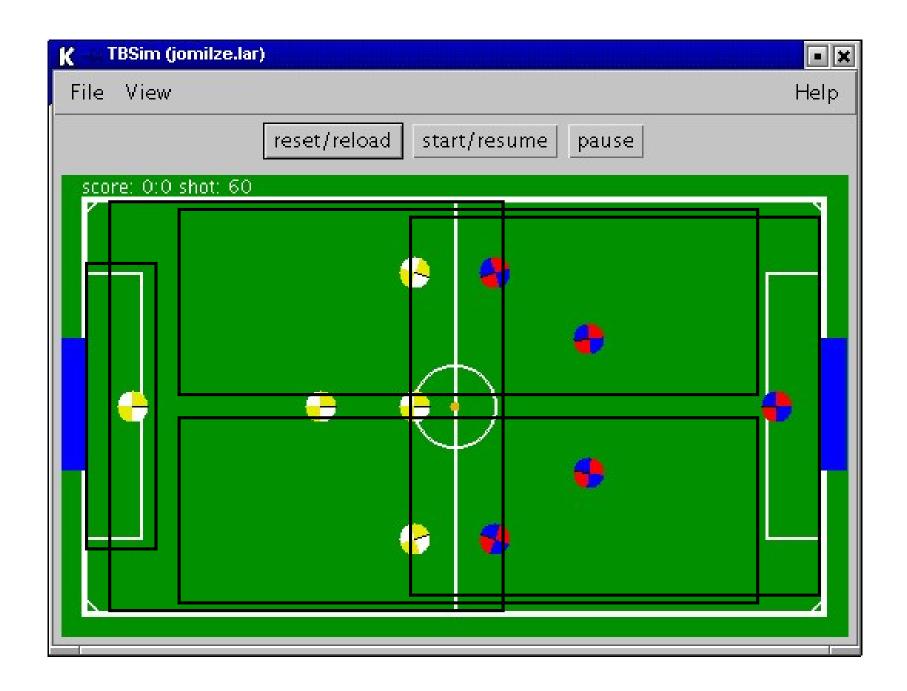
Specifying organisations $\mathcal{M}\mathrm{OISE}^+$



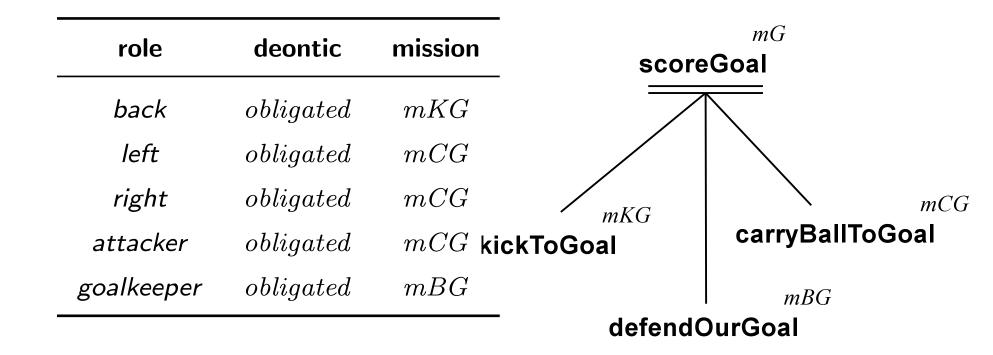
14

The initial organisational structure of the ${\rm JOJTEAM}$

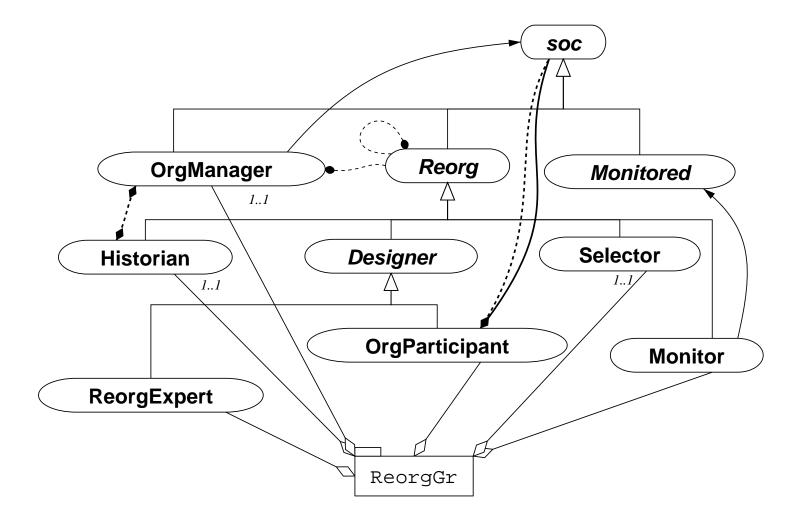




The initial organisational functioning of the $\rm JOJTEAM$

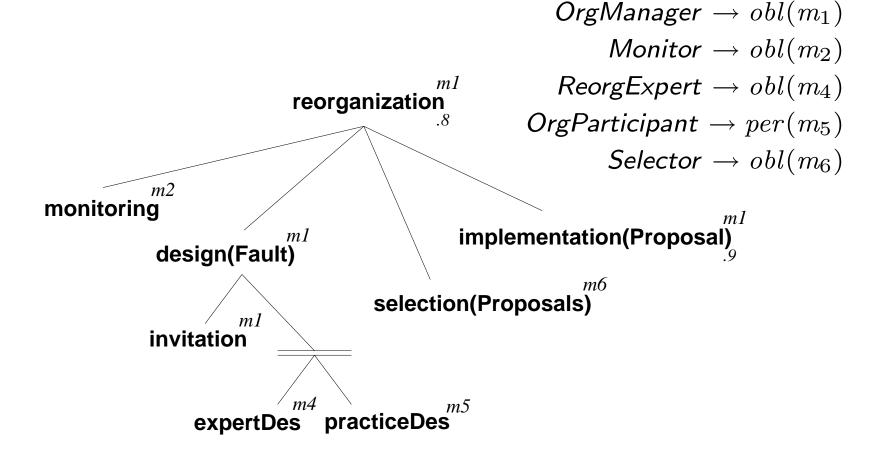


Structural dimension of the **reorganisation**



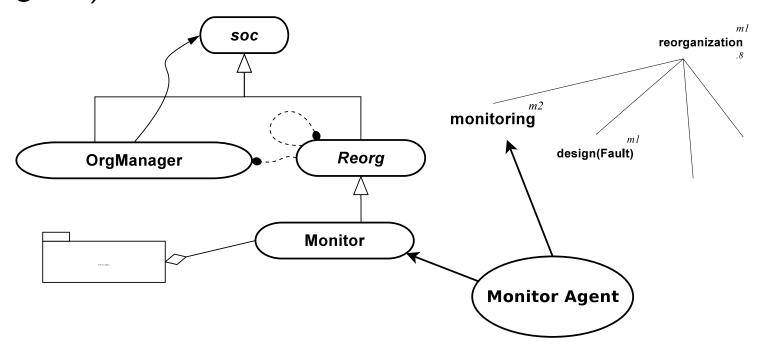
Functional dimension of the reorganisation

deontic relations:



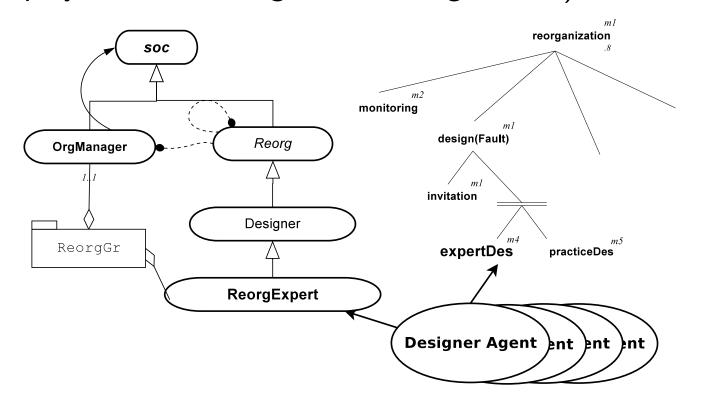
Monitoring goal

• JOJTEAM: the Monitor agent starts a reorganisation each 24.000 simulation step (5 reorganisation each game)



Design goal

 JOJTEAM: 9 designers that always propose the same king of reorganisation (1×1×3, 4×1, increase the players area, change the team goals, ...)



The reorganisation change must be proposed as a reorganisation plan.

• Example:

. . .

- 1. remove all roles from group team;
- 2. create role back extending player;
- 3. set back property area as "-137x40 10x-40";
- 4. add role back into group team;
- 5. define mission mKG as {kickToGoal};
- 6. add mission mKG as obligation for back;

 A plan may change either the structure or the functioning (e.g. add a new mission for the Goalkeeper).

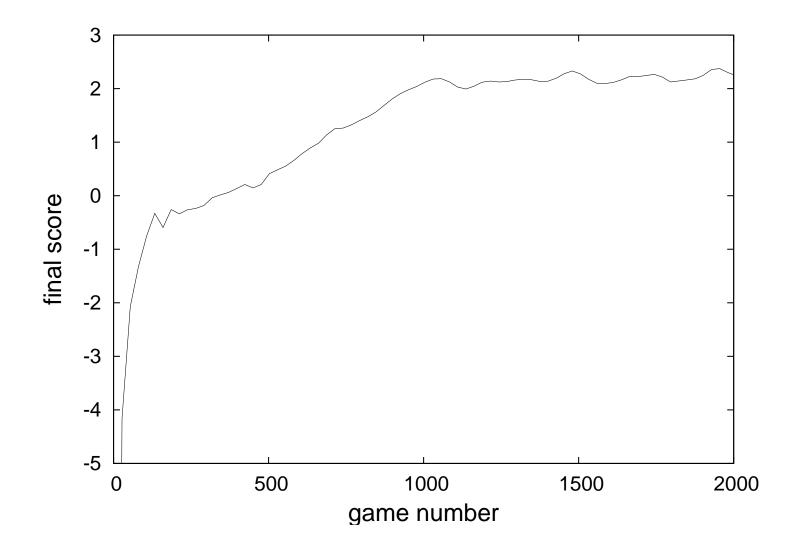
Selection goal

- JOJTEAM: 1 agent that uses Q-Learning the learn when to choose each designer proposal
- State: match time (5 moments) and game score (-2,-1,0,1,2)
- Actions: choose designer 1, choose designer 2, choose designer 9
- Reward: goals

Implementation goal

• The OrgManager agent executes the reorganisation plan selected.

Results

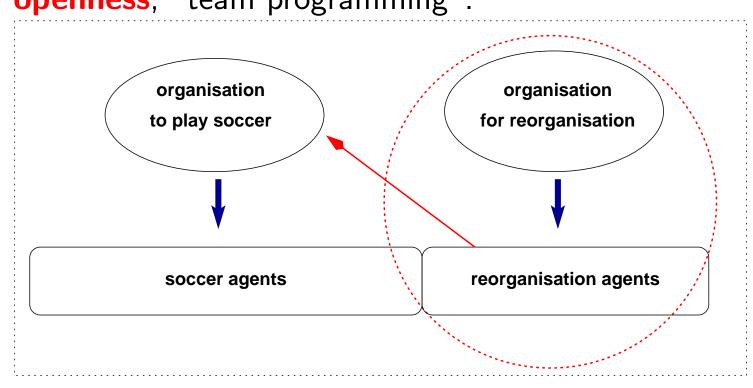


Learnt policy

state (time, score)	action	state (time, score)	action
(0,0)	4×1		
(1,-2)	1x3x1	(2,-2)	4×1
(1,-1)	4×1	(2,-1)	4x1
(1,0)	4×1	(2,0)	nochange
(1,1)	unflexGolie	(2,1)	nochange
(1,2)	nochange	(2,2)	flex
(3,-2)	1x1x3	(4,-2)	4×1
(3,-1)	flexGolie	(4,-1)	nochange
(3,0)	1×1×3	(4,0)	flex
(3,1)	4×1	(4,1)	flex
(3,2)	nochange	(4,2)	nochange

Conclusions

Since the reorganisation is a process like any other, an agent that understand *MOISE*⁺ specification can participate on reorganisation — thus it simplifies openness, "team programming".



- The reorganisation can have many monitoring and designing strategies.
- The reorganisation plans simplifies the design of new organisation and deal with some implementation problems.
- The \mathcal{M} OISE⁺ independence among struncture and functioning simplifies the construction of reorganisation plans.
- An implementation is available at http://www.lti.pcs.usp.br/moise