# Organisation Oriented Programming with $\mathcal{M}$ oise

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## Multi-Agent System (our perspective)





## Outline

- Fundamentals
- Approches
- ► *M*oise (language)
- ORA4MAS (platform)
- Conclusions

(slides written together with O. Boissier, A. Ricci, and R. Bordini)



## Introduction: Some definitions

- Organisations are structured, patterned systems of activity, knowledge, culture, memory, history, and capabilities that are distinct from any single agent [Gasser, 2001]
   organisations are supra-individual phenomena
- ► A decision and communication schema which is applied to a set of actors that together fulfill a set of tasks in order to satisfy goals while guarantying a global coherent state [Malone, 1999]
  → definition by the designer, or by actors, to achieve a purpose
- An organisation is characterised by: a division of tasks, a distribution of roles, authority systems, communication systems, contribution-retribution systems [Bernoux, 1985]

   → pattern of predefined cooperation
- An arrangement of relationships between components, which results into an entity, a system, that has unknown skills at the level of the individuals [Morin, 1977]
  - $\rightsquigarrow$  pattern of emergent cooperation



## Organisation in MAS – a definition

### Pattern of agent cooperation

- with a purpose
- supra-agent
- emergent or
- predefined (by designer or agents)



## Perspective on organisations from EASSS'05 Tutorial (Sichman, Boissier)





## Perspective on organisations from EASSS'05 Tutorial (Sichman, Boissier)

Swarms, AMAS, SASO Self-organisations ...

Organisation is observed. Implicitly programmed in Agents, Interactions, Environment.

Agents don't know about organisation





Social Reasoning Coalition formation Contract Net Protocol ... Organisation is observed. Coalition formation

mechanisms programmed in Agents.

Agents know about organisation



- Programming outside the agents
- Using organisational concepts
- To define a cooperative pattern
- Program = Specification
- By changing the specification, we can change the MAS overall behaviour





First approach

 Agents read the program and follow it





## Second approach

- Agents are forced to follow the program
- Agents are rewarded if they follow the program





Second approach

. . .

- Agents are forced to follow the program
- Agents are rewarded if they follow the program





Components

- Programming language (OML)
- Platform (OMI)
- Integration to agent architectures and to environment



# Components of OOP: Organisation Modelling Language (OML)

- Declarative specification of the organisation(s)
- Specific constraints, norms and cooperation patterns imposed on the agents
- Based on an organisational model
  - e.g. AGR [Ferber and Gutknecht, 1998], TeamCore [Tambe, 1997], Islander [Esteva et al., 2001], Moise<sup>+</sup> [Hübner et al., 2002], Opera [Dignum and Aldewereld, 2010], 2OPL [Dastani et al., 2009], THOMAS [Criado et al., 2011],



## Components of OOP:

Organisation Management Infrastructure (OMI)

 Coordination mechanisms, i.e. support infrastructure e.g. MadKit [Gutknecht and Ferber, 2000], karma [Pynadath and Tambe, 2003],

 Regulation mechanisms, i.e. governance infrastructure e.g. Ameli [Esteva et al., 2004], *S-M*oise<sup>+</sup> [Hübner et al., 2006], ORA4MAS [Hübner et al., 2009],

► Adaptation mechanisms, i.e. reorganisation infrastructure



# Components of OOP: Integration mechanisms

- Agent integration mechanisms allow agents to be aware of and to deliberate on:
  - entering/exiting the organisation
  - modification of the organisation
  - obedience/violation of norms
  - sanctioning/rewarding other agents
  - e.g. *J*-*M*oise<sup>+</sup> [Hübner et al., 2007], Autonomy based reasoning [Carabelea, 2007], *ProsA*<sub>2</sub> Agent-based reasoning on norms [Ossowski, 1999], ...
- Environment integration mechanisms transform organisation into embodied organisation so that:
  - organisation may act on the environment (e.g. enact rules, regimentation)
  - environment may act on the organisation (e.g. count-as rules)
  - e.g [Piunti et al., 2009b, Okuyama et al., 2008, de Brito et al., 2014]



# Motivations for OOP: **Applications** point of view

Current applications show an increase in

- Number of agents
- Duration and repetitiveness of agent activities
- Heterogeneity of the agents
- Number of designers of agents
- Agent ability to act and decide
- Openness, scalability, dynamism
- More and more applications require the integration of human communities and technological communities (ubiquitous and pervasive computing), building connected communities (ICities) in which agents act on behalf of users
  - Trust, security, ..., flexibility, adaptation



# Motivations for OOP: **Constitutive** point of view

 Organisation helps the agents to cooperate with other agents by defining common cooperation schemes

- global tasks
- protocols
- groups, responsibilities
- e.g. 'to bid' for a product on eBay is an institutional action only possible because eBay defines rules for that very action
  - the bid protocol is a constraint but it also creates the action
- e.g. when a soccer team wants to play match, the organisation helps the members of the team to synchronise actions, to share information, etc



# Motivations for OOP: **Normative** point of view

- ► MAS have two properties which seem contradictory:
  - a global purpose
  - autonomous agents
  - While the autonomy of the agents is essential, it may cause loss in the global coherence of the system and achievement of the global purpose
- Embedding norms within the organisation of an MAS is a way to constrain the agents' behaviour towards the global purposes of the organisation, while explicitly addressing the autonomy of the agents within the organisation
  - $\rightsquigarrow$  Normative organisation
  - e.g. when an agent adopts a role, it adopts a set of behavioural constraints that support the global purpose of the organisation.

It may decide to obey or disobey these constraints



# Motivations for OOP: **Agents** point of view

An organisational specification is required to enable agents to "reason" about the organisation:

- to decide to enter into/leave from the organisation during execution
  - → Organisation is no more closed
- to change/adapt the current organisation
  - → Organisation is no more static
- to obey/disobey the organisation
  - $\rightsquigarrow$  Organisation is no more a regimentation



# Motivations for OOP: **Organisation** point of view

An organisational specification is required to enable the organisation to "reason" about itself and about the agents in order to ensure the achievement of its global purpose:

- to decide to let agents enter into/leave from the organisation during execution
  - → Organisation is no more closed
- to decide to let agents change/adapt the current organisation

 $\rightsquigarrow$  Organisation is no more static and blind

 to govern agents behaviour in the organisation (i.e. monitor, enforce, regiment)

 $\rightsquigarrow$  Organisation is no more a regimentation



## Some OOP approaches

- ► AGR/Madkit [Ferber and Gutknecht, 1998]
- ► STEAM/Teamcore [Tambe, 1997]
- ► ISLANDER/AMELI [Esteva et al., 2004]
- ▶ Opera/Operetta [Dignum and Aldewereld, 2010]
- PopOrg [Rocha Costa and Dimuro, 2009]
- > 20PL [Dastani et al., 2009]
- ▶ THOMAS [Criado et al., 2011],

#### ► ...

### Fundamentals

Some OOP approaches

### The $\mathcal{M}$ oise framework

Moise Organisation Modelling Language (OML) ORA4MAS Organisation Management Infrastructure (OMI) Jason and ORA4MAS integration

## $\mathcal{M}$ oise Framework

- OML (language)
  - Tag-based language

     (issued from Moise [Hannoun et al., 2000],
     Moise<sup>+</sup> [Hübner et al., 2002],
     MoiseInst [Gâteau et al., 2005])
- OMI (infrastructure)
  - developed as an artifact-based working environment (ORA4MAS [Hübner et al., 2009] based on CArtAgO nodes, refactoring of S-Moise<sup>+</sup> [Hübner et al., 2006] and Synai [Gâteau et al., 2005])
- Integrations
  - Agents and Environment (c4Jason, c4Jadex [Ricci et al., 2009])
  - Environment and Organisation ([Piunti et al., 2009a])
  - Agents and Organisation ( $\mathcal{J}$ - $\mathcal{M}$ oise<sup>+</sup> [Hübner et al., 2007])



## $\mathcal{M}$ oise OML meta-model (partial view)



## $\mathcal{M}$ oise Modelling Dimensions



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## $\mathcal{M}$ oise OML

- OML for defining organisation specification and organisation entity
- ► Three independent dimensions [Hübner et al., 2007] (→ well adapted for the reorganisation concerns):
  - Structural: Roles, Groups
  - Functional: Goals, Missions, Schemes
  - Normative: Norms (obligations, permissions, interdictions)
- Abstract description of the organisation for
  - the designers
  - the agents
    - $\rightsquigarrow \mathcal{J}\text{-}\mathcal{M}\text{oise}^+$  [Hübner et al., 2007]
  - the Organisation Management Infrastructure
    - → ORA4MAS [Hübner et al., 2009]



## Structural Specification

Specifies the structure of an MAS along three levels:

- Individual with Role
- Social with Link
- Collective with Group
- Components:
  - Role: label used to assign rights and constraints on the behavior of agents playing it
  - Link: relation between roles that directly constrains the agents in their interaction with the other agents playing the corresponding roles
  - Group: set of links, roles, compatibility relations used to define a shared context for agents playing roles in it



## Structural Specification Example



Graphical representation of structural specification of 3-5-2 Joj Team



## **Functional Specification**

- Specifies the expected behaviour of an MAS in terms of goals along two levels:
  - Collective with Scheme
  - Individual with Mission
- Components:
  - Goals:
    - Achievement goal (default type). Goals of this type should be declared as satisfied by the agents committed to them, when achieved
    - Maintenance goal. Goals of this type are not satisfied at a precise moment but are pursued while the scheme is running. The agents committed to them do not need to declare that they are satisfied
  - Scheme: global goal decomposition tree assigned to a group
    - Any scheme has a root goal that is decomposed into subgoals
  - Missions: set of coherent goals assigned to roles within norms



## Functional Specification Example



Graphical representation of social scheme "side\_attack" for joj team



## Goal States



waiting initial state

enabled goal pre-conditions are satisfied & scheme is well-formed

satisfied agents committed to the goal have achieved it impossible the goal is impossible to be satisfied



## Normative Specification

- Explicit relation between the functional and structural specifications
- Permissions and obligations to commit to missions in the context of a role
- Makes explicit the normative dimension of a role



## Norm Specification – example

role	deontic	mission		TTF
back	obliged	m1	get the ball, go	1 minute
left	obliged	<i>m</i> 2	be placed at, kick	3 minute
right	obliged	<i>m</i> 2		1 day
attacker	obliged	т3	kick to the goal,	30 seconds



## Organisational Entity





## Organisation Entity Dynamics

- 1. Organisation is created (by the agents)
  - instances of groups
  - instances of schemes
- 2. Agents enter into groups adopting roles
- 3. Groups become responsible for schemes
  - Agents from the group are then obliged to commit to missions in the scheme
- 4. Agents commit to missions
- 5. Agents fulfil mission's goals
- 6. Agents leave schemes and groups
- 7. Schemes and groups instances are destroyed



# Organisation management infrastructure (OMI)

## Responsibility

 Managing – coordination, regulation – the agents' execution within organisation defined in an organisational specification



(e.g. MadKit, AMELI, S- $\mathcal{M}$ oise<sup>+</sup>, THOMAS, ...)



## Organisational artifacts in ORA4MAS



- based on A&A and Moise
- agents create and handle organisational artifacts
- artifacts in charge of regimentations, detection and evaluation of norms compliance
- agents are in charge of decisions about sanctions
- distributed solution

## ORA4MAS – GroupBoard artifact



## Observable Properties:

- specification: the specification of the group in the OS (an object of class moise.os.ss.Group)
- players: a list of agents playing roles in the group.
   Each element of the list is a pair (agent x role)
- schemes: a list of scheme identifiers that the group is responsible for

## ORA4MAS – GroupBoard artifact



## Operations:

- adoptRole(role): the agent executing this operation tries to adopt a role in the group
- leaveRole(role)
- addScheme(schid): the group starts to be responsible for the scheme managed by the SchemeBoard schld
- removeScheme(schid)

## ORA4MAS – SchemeBoard artifact



## **Observable Properties:**

- specification: the specification of the scheme in the OS
- groups: a list of groups responsible for the scheme
- players: a list of agents committed to the scheme.
   Each element of the list is a pair (agent, mission)
- goals: a list with the current state of the goals
- obligations: list of obligations currently active in the scheme

## ORA4MAS – SchemeBoard artifact



## Operations:

- commitMission(mission) and leaveMission: operations to "enter" and "leave" the scheme
- goalAchieved(goal): defines that some goal is achieved by the agent performing the operation
- setGoalArgument(goal, argument, value): defines the value of some goal's argument

## Environment integration: constitutive rules

## Count-As rule

An event occurring on an artifact, in a particular context, may count-as an institutional event

 $\rightsquigarrow$  indirect automatic updating of the organisation



## Agent integration

- Agents can interact with organisational artifacts as with ordinary artifacts by perception and action
- Any Agent Programming Language integrated with CArtAgO can use organisational artifacts

Agent integration provides some "internal" tools for the agents to simplify their interaction with the organisation:

- maintenance of a local copy of the organisational state
- production of organisational events
- provision of organisational actions



## Organisational actions in Jason I

```
Example (GroupBoard)
```

```
joinWorkspace("ora4mas",04MWsp);
makeArtifact(
    "auction",
    "ora4mas.nopl.GroupBoard",
    ["auction-os.xml", auctionGroup],
    GrArtId);
adoptRole(auctioneer);
focus(GrArtId);
...
```



## Organisational actions in Jason II

```
Example (SchemeBoard)
makeArtifact(
   "sch1".
   "ora4mas.nopl.SchemeBoard",
   ["auction-os.xml", doAuction],
   SchArtId);
focus(SchArtId);
addScheme(Sch);
commitMission(mAuctioneer)[artifact_id(SchArtId)];
. . .
```



## Organisational perception

When an agent focus on an Organisational Artifact, the observable properties (Java objects) are translated to beliefs with the following predicates:

- specification
- play(agent, role, group)
- commitment(agent, mission, scheme)
- goalState(scheme, goal, list of committed agents, list of agent that achieved the goal, state of the goal)
- obligation(agent,norm,goal,dead line)



Organisational perception – example

# Inspection of agent **bob** (cycle #0)

commitment(bob,mManager,"sch2")[artifact id(cobj 4).c Beliefs cept),artifact name(cobj 4,"sch2"),artifact type(cobj 4,"ora4m commitment(bob,mManager,"sch1")[artifact\_id(cobj\_3).c cept),artifact\_name(cobj\_3,"sch1"),artifact\_type(cobj\_3,"ora4m current\_wsp(cobj\_1,"ora4mas","308b05b0-2994-4fe8 formationStatus(ok)[artifact\_id(cobj\_2),obs\_prop\_id("obs\_i+ obj 2,"mypaper"),artifact\_type(cobj\_2,"ora4mas.nopl.GroupBo goalState("sch2",wp,[bob],[bob],satisfied)[artifact\_id(cot



## Handling organisational events in Jason

Whenever something changes in the organisation, the agent architecture updates the agent belief base accordingly producing events (belief update from perception)

Example (new agent entered the group)

+play(Ag,boss,GId) <- .send(Ag,tell,hello).

Example (change in goal state and norm violation)

+goalState(Scheme,wsecs,\_,\_,satisfied)

- : .my\_name(Me) & commitment(Me,mCol,Scheme)
- <- leaveMission(mColaborator,Scheme).

+normFailure(N) <- .print("norm failure event: ", N).</pre>



## Typical plans for obligations

+obligation(Ag,Norm,committed(Ag,Mission,Scheme),DeadLine)

- : .my\_name(Ag)
- <- .print("I am obliged to commit to ",Mission); commitMission(Mission,Scheme).

+obligation(Ag,Norm,achieved(Sch,Goal,Ag),DeadLine)

- : .my\_name(Ag)
- <- .print("I am obliged to achieve goal ",Goal); !Goal[scheme(Sch)]; goalAchieved(Goal,Sch).

+obligation(Ag,Norm,What,DeadLine)



## Summary – OOP

Organisation is a complex and rich dimension in MAS:

- represented in different "eyes": designer – observer – agents
- expressed with two points of view: agent-centred vs. organisation-centred
- using multiple models: e.g. Joint intentions, shared plans, dependence theory, ...
- Organisation is built to fulfill different aims
  - to help the cooperation between the agents,
  - to control the cooperation between the agents (forgetting or not the autonomy of the agents)



## $\mathsf{Summary} - \mathcal{M}\mathsf{o}\mathsf{ise}$

- Ensures that the agents follow some of the constraints specified for the organisation
- Helps the agents to work together
- The organisation is interpreted at runtime, it is not hardwired in the agents code
- ▶ The agents 'handle' the organisation (i.e. their artifacts)
- It is suitable for open systems as no specific agent architecture is required

All available as open source at

http://moise.souceforge.net



TOC

Fundamentals

Some OOP approaches

The  $\mathcal{M}$ oise framework

Moise Organisation Modelling Language (OML) ORA4MAS Organisation Management Infrastructure (OMI) Jason and ORA4MAS integration



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