

# Normative Programming

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# Agenda

- ◆ Norms in MAS
- ◆ Programming Norms

# (regulative) Norms

- ◆ Expected (social) behavior
- ◆ Usual elements [Elinor Ostrom]
  - ◆ when a norm is applicable
  - ◆ to whom it applies
  - ◆ deontic operator
  - ◆ aim
  - ◆ [sanction]

when an auction is **finished**, the **bidder** is **obliged** to **pay** its offer, otherwise s/he will be **fined**

# Norms in MAS

## ◆ Perspectives

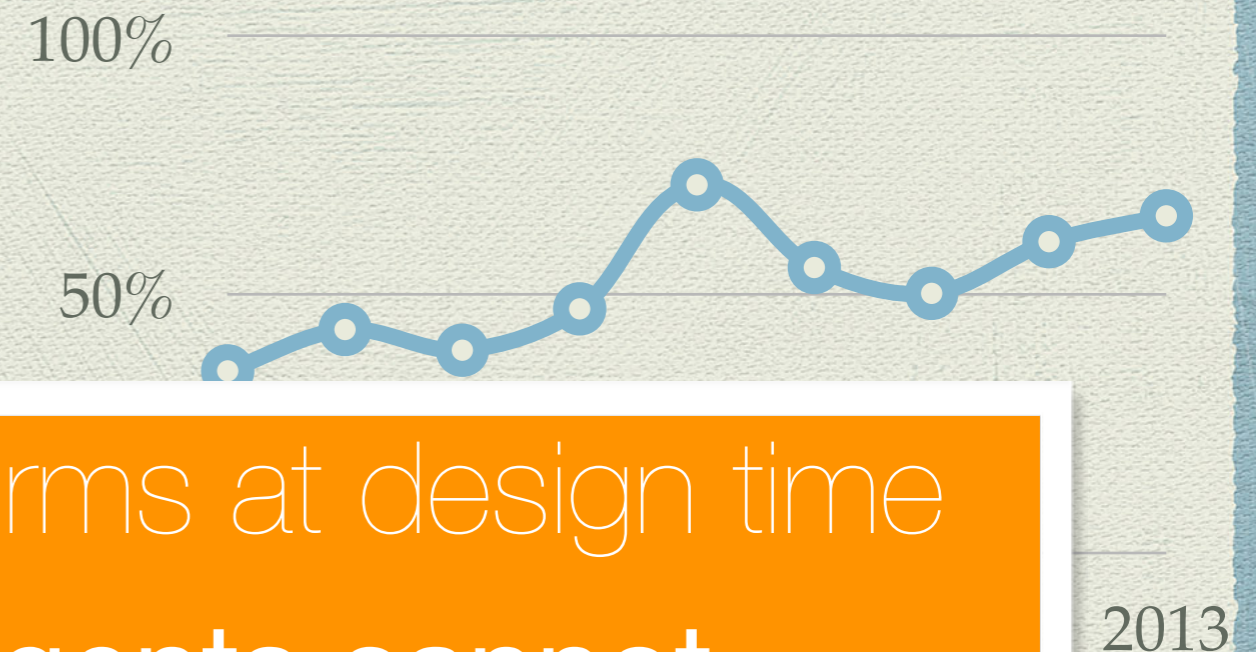
◆ AOSE (design time)

◆ COIN (run time)

## ◆ Hot Topic

◆ 52% (83/161) papers

Norms @ COIN



norms at design time

\* agents cannot reason about them

\* norms cannot be changed at runtime

2013

# Why norms (at runtime)?

- ◆ To deal with open MAS and autonomous agents
  - ◆ “agents can enter or leave freely and neither the number, nor the behaviour, nor the way in which the agents interact and access shared resources can be known at design time” [Piunti]

# Why norms (at runtime)?

- ◆ To program at a higher level
  - ◆ To program the overall system and not a machine, a process, an object, or an agent
  - ◆ The MAS specification does not need to be reduced to lower level concepts until it can be programmed (e.g. as processes)

# Agents level

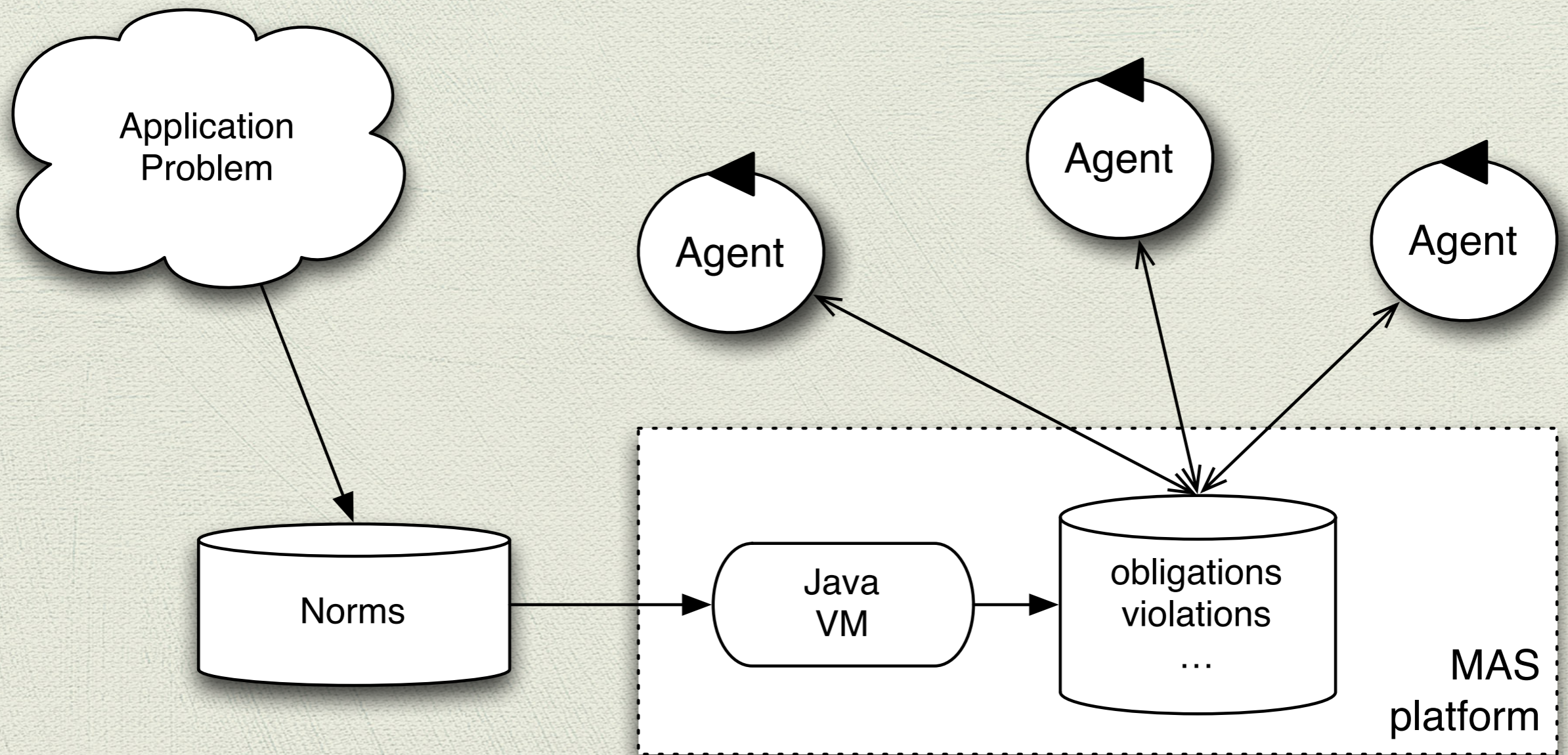
- ◆ Norm aware reasoning
  - ◆ recognition
  - ◆ adoption
  - ◆ compliance
  - ◆ revision

# System level

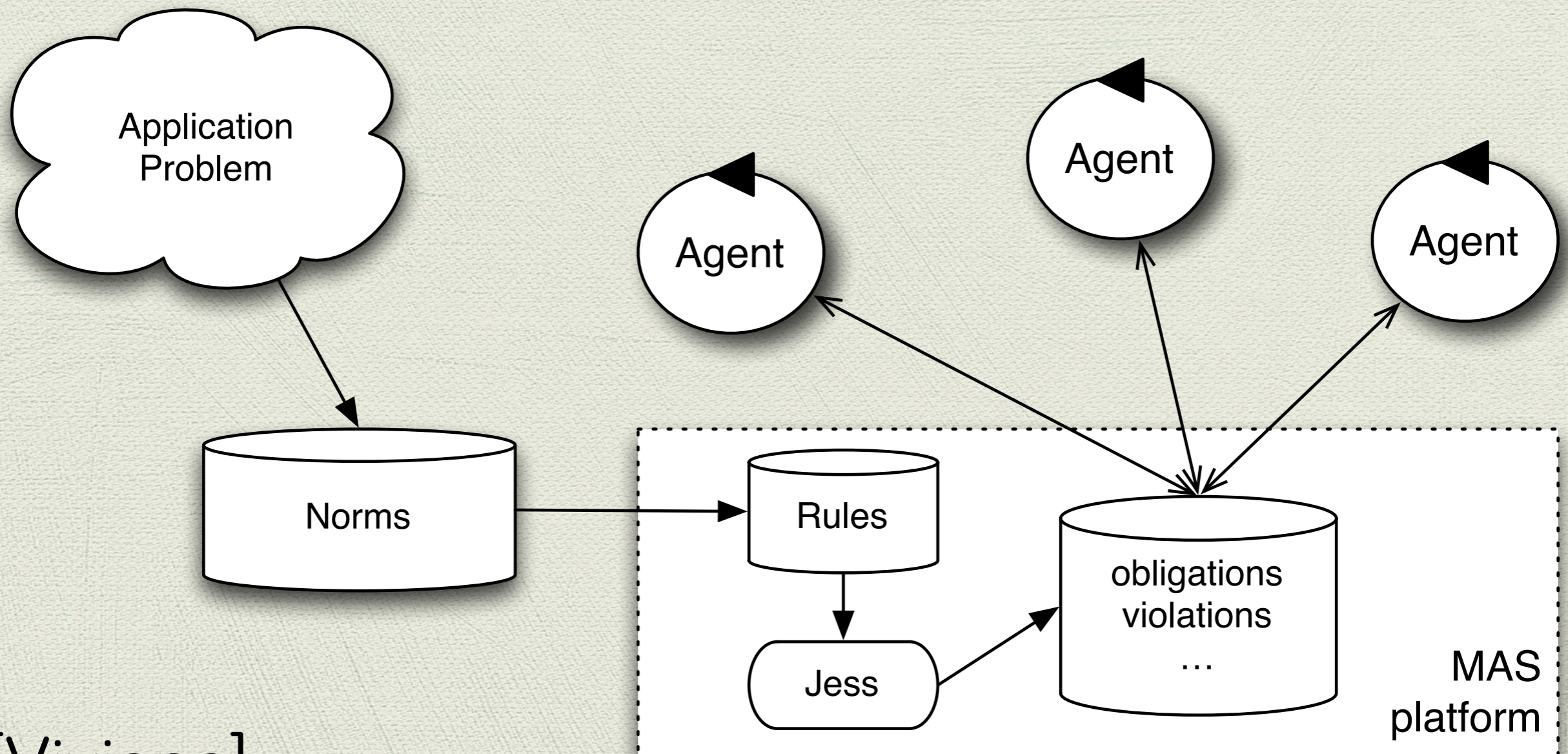
- ◆ The system platform manages norms
  - ◆ independent from the agents
- ◆ Mechanisms
  - ◆ regimentation
  - ◆ enforcement (detection, sanctions, reputation, ...)



# Normative Platform



# Normative Platform



[Viviane]

# Normative programming

objectives

control [malicious] agents

programming an MAS is not programming (only) agents

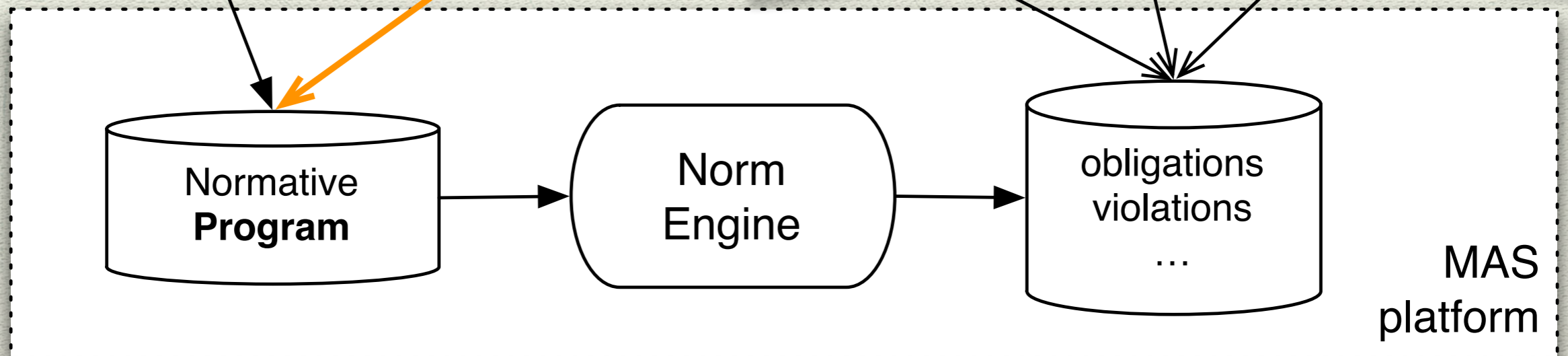
to achieve  
] goals

simplifies reasoning about the institution

agents can change the norms

Application Problem

Agent



MAS platform

# Example: Situating Artificial Institution (SAI)

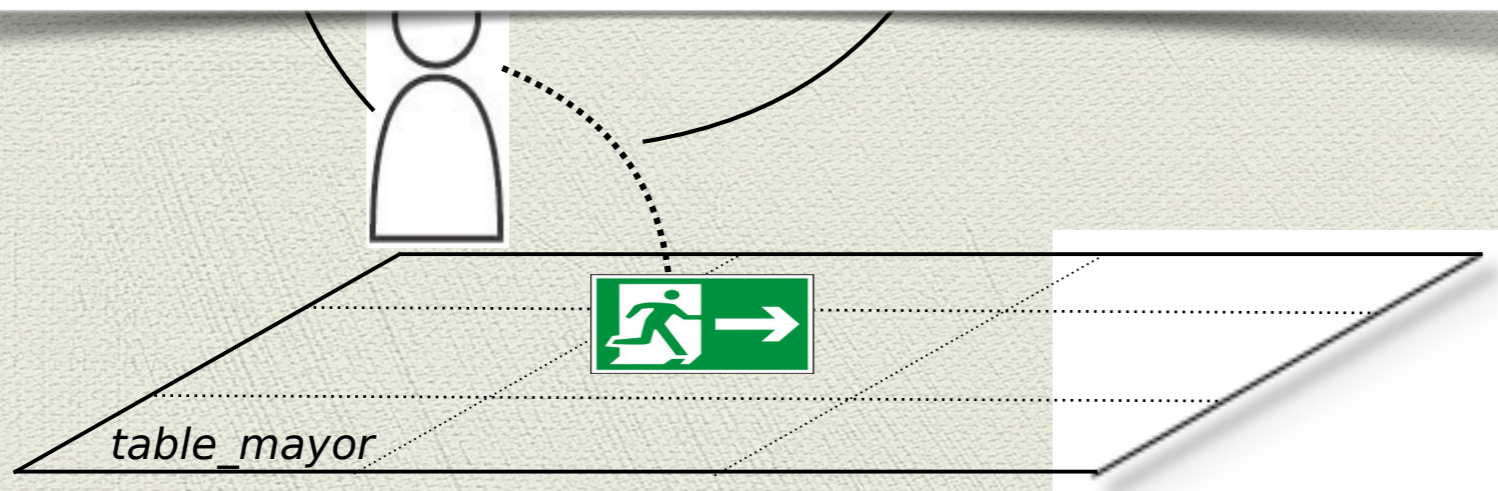
The **mayor** is obliged to **command evacuation**

*Norms*

The **mayor** is obliged to  
command **evacuation**  
the **area is risky**

*Status  
Functions*

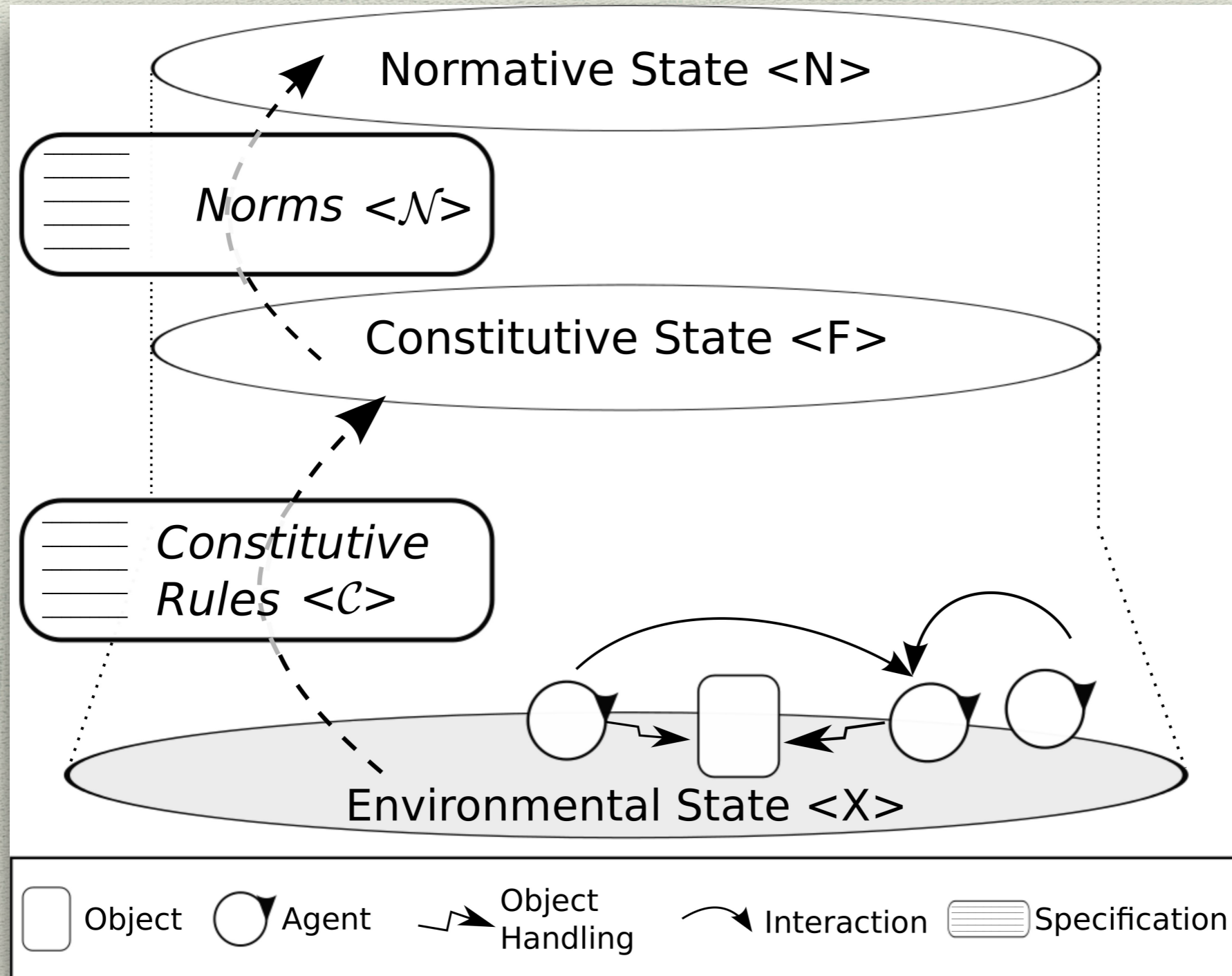
*Constitutive  
Rules*



*Environment*

[Brito]

# Example: Situating Artificial Institution (SAI)



[Brito]

# Example: 2OPL

## Example (Train Station)

Facts:

```
{ -at_platform , -in_train , -ticket }
```

Effects:

```
{ -at_platform }      enter      { at_platform },  
{ -ticket }          buy_ticket  { ticket },  
{ at_platform , -in_train }  
                      embark  
                      { -at_platform, in_train }
```

Counts\_as rules:

```
{ at_platform , -ticket } => { viol_ticket },  
{ in_train , -ticket }   => { viol_|_ }
```

Sanction\_rules:

```
{ viol_ticket } => { fined_10 }
```

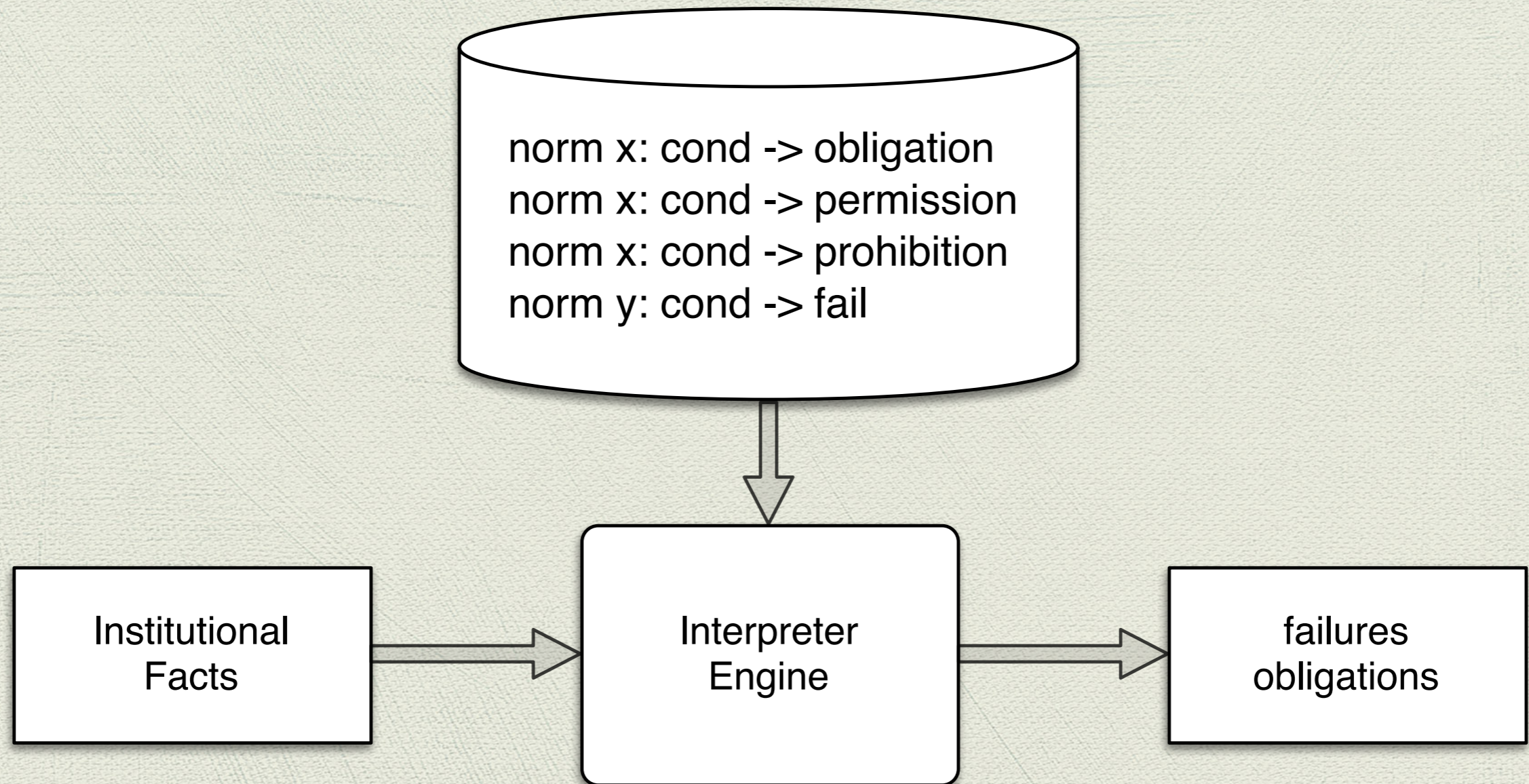
[Mehdi]

# Example: NPL

- norm auction\_pay:
  - finished(Auction) &
  - play(Ag,bidder,Auction)
- > obligation(Ag,
  - winner(Ag,Auction),
  - paid(Auction),
  - 'now + 2 days')

when an auction is finished, the bidder is obliged to pay its offer, otherwise s/he will be **fined**

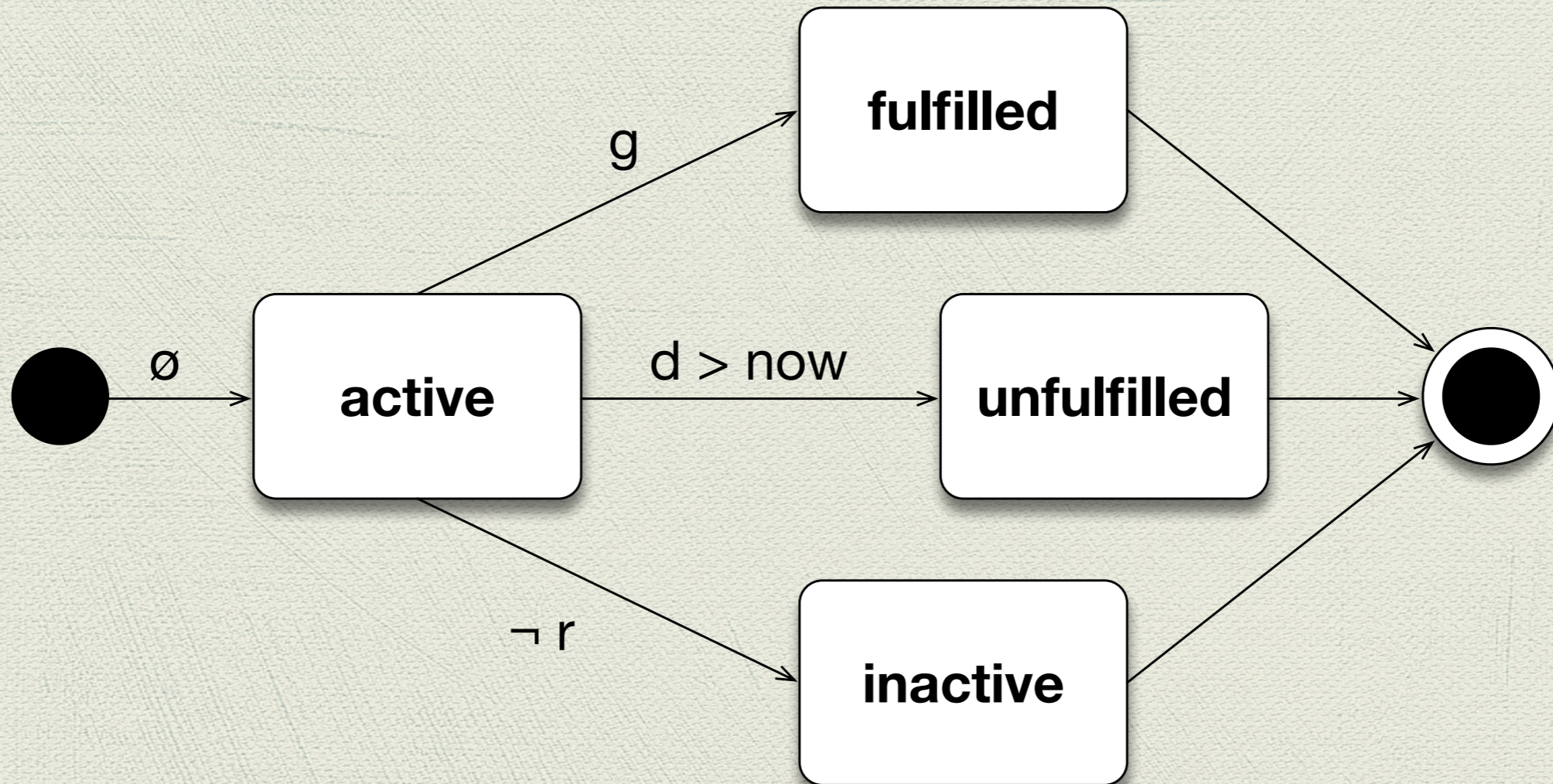
# NPL Interpreter





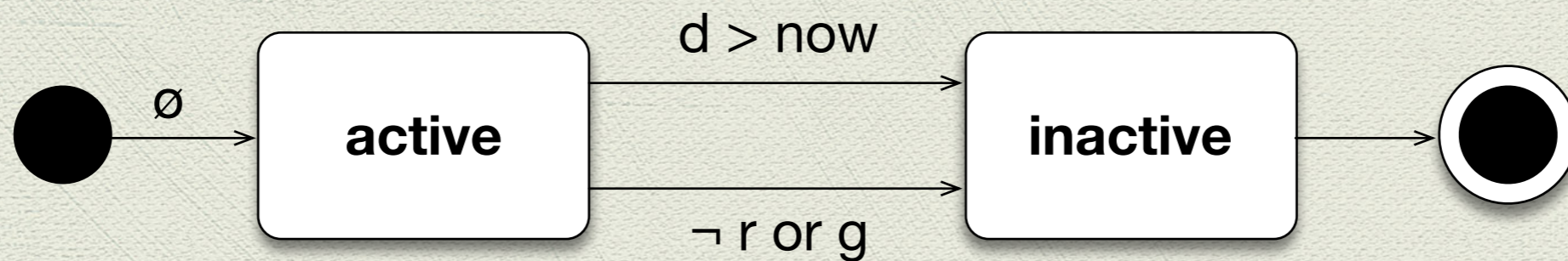
# Obligations in NPL

norm  $n$ :  $\emptyset \rightarrow \text{obligation}(a, r, g, d)$



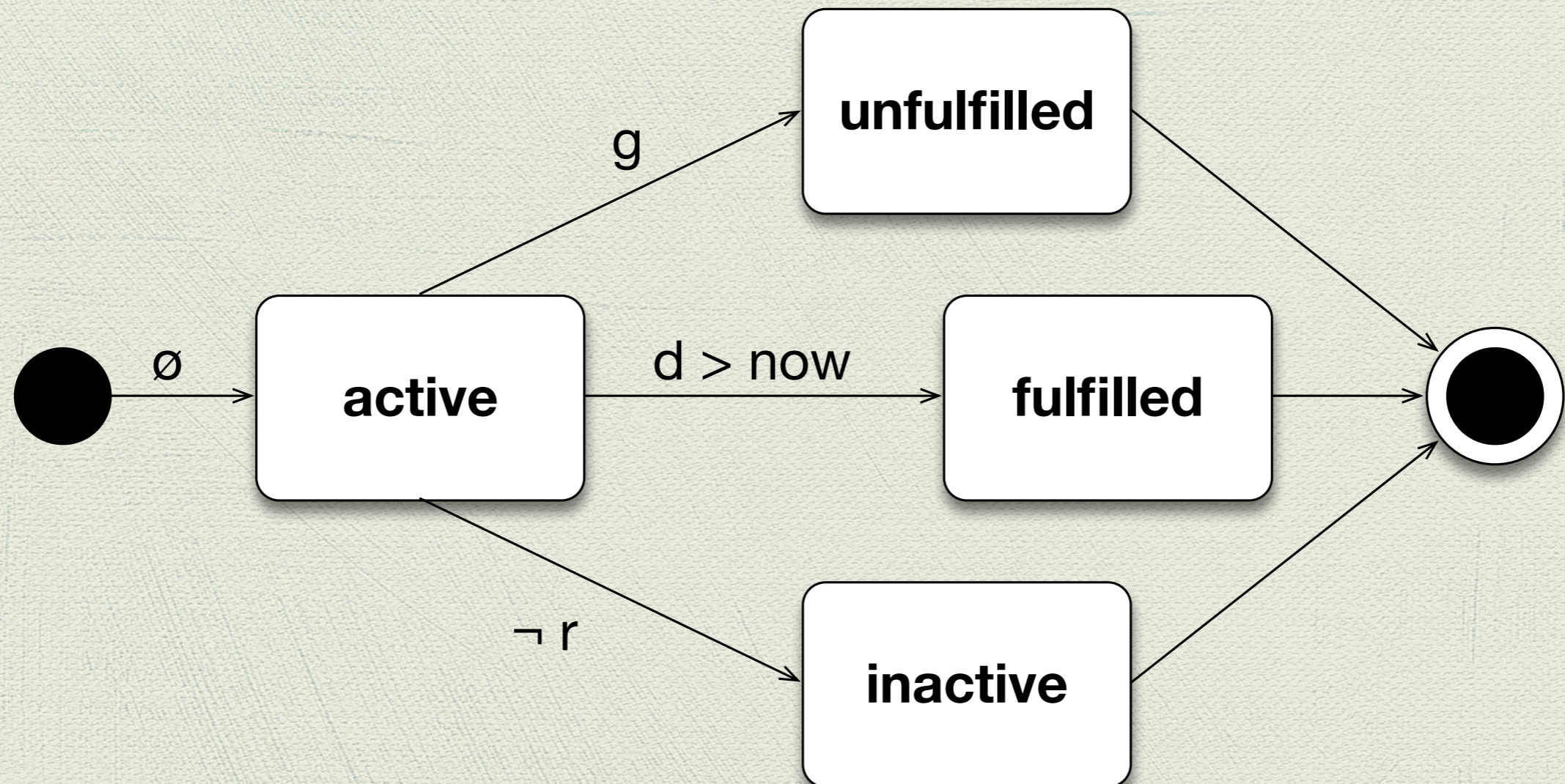
# Permissions in NPL

norm n:  $\emptyset \rightarrow \text{permission}(a,r,g,d)$

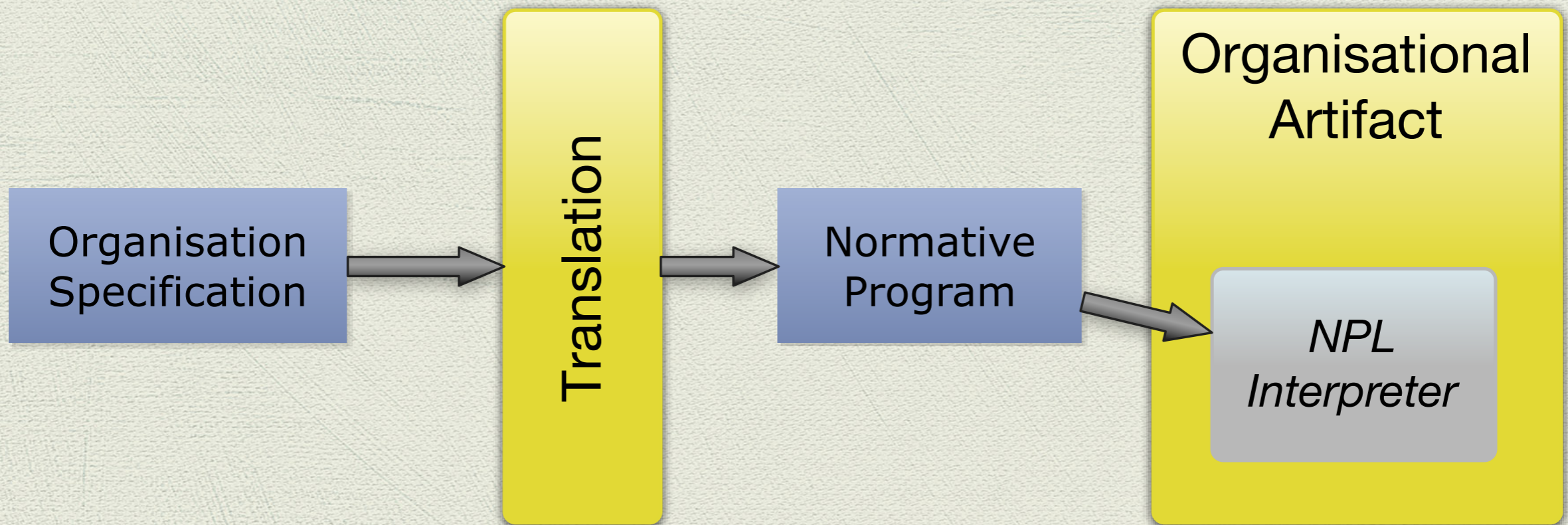


# Prohibition in NPL

norm n:  $\ominus \rightarrow \text{prohibition}(a,r,g,d)$



# Example: NOPL



# Example: NOPL

◆ norm ngoa:

committed(A,M,S) &

goal(M,G, achievement, D) &

well\_formed(S)

-> obligation(A,

enabled(G,S),

achieved(S,G),

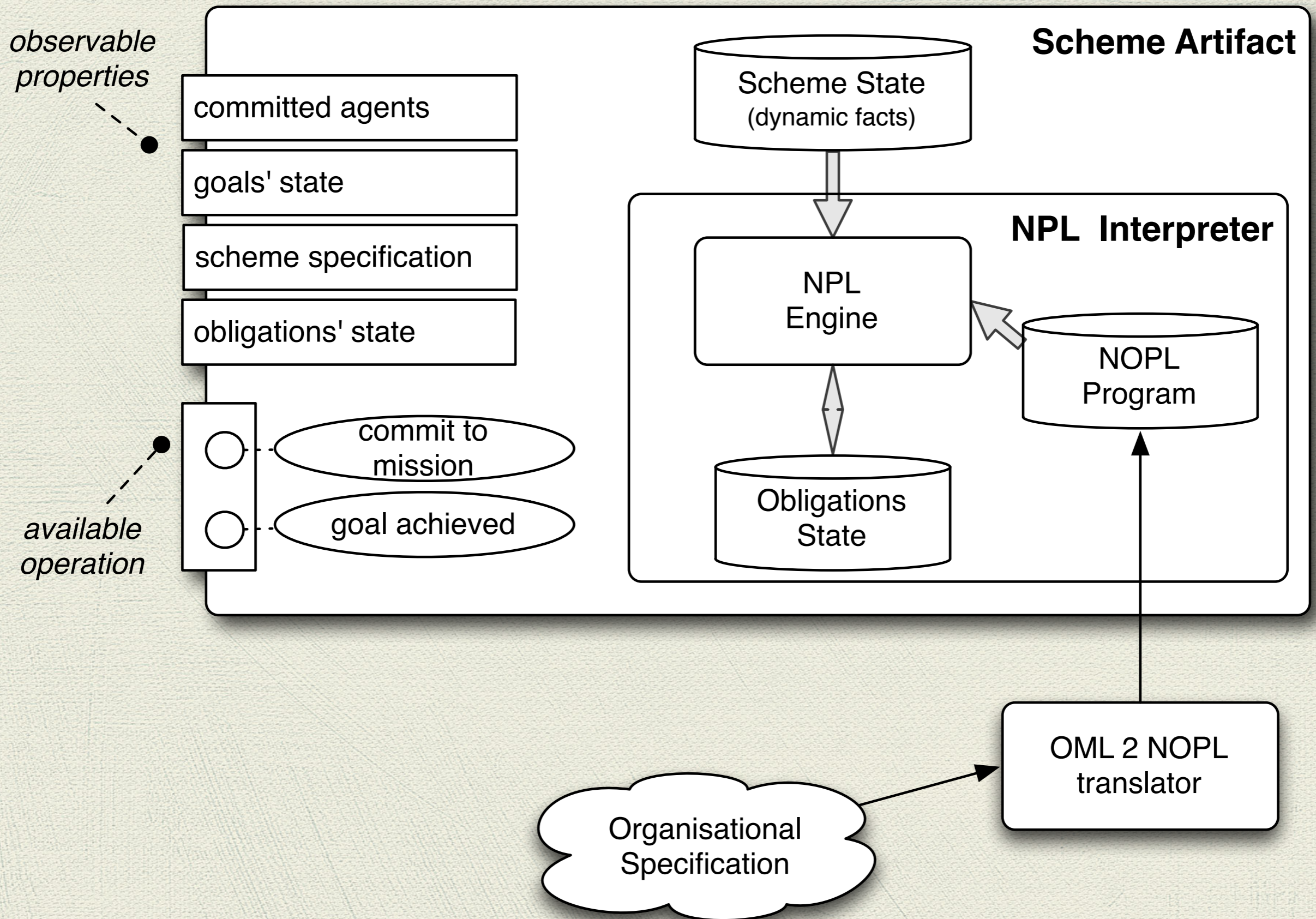
'now' + D)

# Example: NOPL

- ◆ norm ngoa:
  - committed(A,M,S) &
  - goal(M,G, performance, D) &
  - well\_formed(S)
- > obligation(A,
  - enabled(G,S),
  - done(S,G,A),
  - 'now' + D)

# Example: NOPL

- ◆ norm mission\_cardinality:  
scheme\_mission(M,\_,MMax) &  
mplayers(M,S,MP) & MP > MMax  
-> fail(mission\_cardinality).
- ◆ norm mission\_cardinality:  
scheme\_mission(M,\_,MMax) &  
mplayers(M,S,MP) & MP < MMax  
responsible(Gr,S)  
-> obligation(A, plays(A,editor,Gr),  
committed(A,ms,\_), 'now'+ '1 hour').





# Alg. for org actions

- 1:  $oe$  is the state of the organisation managed by the artifact
- 2:  $p$  is the current NOPL program
- 3:  $npi$  is the NPL interpreter
- 4: **when** an operation  $o$  is triggered by agent  $a$  **do**
- 5:      $oe' \leftarrow oe$  // creates a “backup” of the current  $oe$
- 6:     executes operation  $o$  to change  $oe$
- 7:      $f \leftarrow$  a list of predicates representing  $oe$
- 8:      $r \leftarrow npi(p, f)$  // runs the interpreter for the new state
- 9:     **if**  $r = \text{fail}$  **then**
- 10:          $oe \leftarrow oe'$  // restore the backup state
- 11:         **return** fail operation  $o$
- 12:     **else**
- 13:         update obligations in the observable properties
- 14:         **return** succeed operation  $o$

organisation entity **normative state** normative facts normative program specification

**Normative State: *scheme(build\_house\_sch)***

state	agent	reason (norm)	goal
active	companyD12	ngoal("bhsch",prepare_site,site_prepared)	achieved("bhsch",site_prepared,companyD12)
unfulfilled	companyD12	ngoal("bhsch",prepare_site,site_prepared)	achieved("bhsch",site_prepared,companyD12)

History

fulfilled: obligation(companyC1,n10,committed(companyC1,paint\_house,"bhsch"),1314377299506)[created  
 fulfilled: obligation(companyA,n8,committed(companyA,install\_plumbing,"bhsch"),1314377299549)[crea  
 fulfilled: obligation(companyC1,n9,committed(companyC1,install\_electrical\_system,"bhsch"),13143772  
 fulfilled: obligation(companyD8,n7,committed(companyD8,fit\_doors,"bhsch"),1314377299550)[created(1  
 fulfilled: obligation(companyD8,n6,committed(companyD8,fit\_windows,"bhsch"),1314377299551)[created  
 created: obligation(companyD12,ngoal("bhsch",prepare\_site,site\_prepared),achieved("bhsch",site\_p  
 created: obligation(companyE,ngoal("bhsch",prepare\_floors,floors\_laid),achieved("bhsch",floors\_laid  
 fulfilled: obligation(companyE,ngoal("bhsch",prepare\_floors,floors\_laid),achieved("bhsch",floors\_laid  
 unfulfilled: obligation(companyD12,ngoal("bhsch",prepare\_site,site\_prepared),achieved("bhsch",site\_p

<http://moise.sf.net>

bhsch hsh\_group

# What is the (best) language to program the institutional platform?

- ◆ java?
- ◆ rules?
- ◆ norms?

- ◆ translation instead of coding
- ◆ agent can reason on norms or institutional specification (both are available)

## ORA4MAS

- \* 80% code NOPL (obligations)
- \* 10% code CArtAgO (agent interface)
- \* 10% code Java

# Open issues

- ◆ monitoring “big brother”
  - ◆ how to get all data
  - ◆ how to deal with so much data on time
- ◆ regimentations or sanction
  - ◆ how to chose the best strategy
- ◆ integration with constitutive rules
- ◆ normative “modules”

# Summary

- ◆ Normative Programming
  - ◆ few code with a lot of meaning
  - ◆ at runtime
  - ◆ for agents to reason about the institution
  - ◆ for designers (and agents) to specify institutions